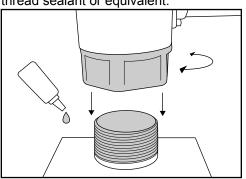
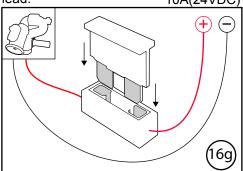
Quick Attack Pkg 1 Install Guide: Monitor & Nozzle

1. A. Tighten Sidewinder EXM monitor to base or Quick Connect using Loctite 592 thread sealant or equivalent.



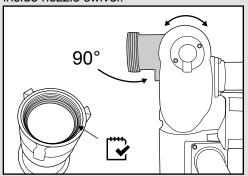
B. Add a 20A(12VDC)* fuse between RED controller lead and positive power lead. *10A(24VDC)



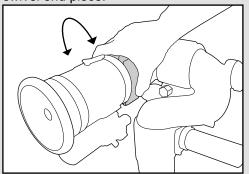
NOTE: We recommend using 16 AWG for monitor power and ground. See installation instructions section of the Sidewinder EXM manual (98317000) for length to gauge recommendations.

NOTE: If a Quick Connect is being installed, please refer to the Quick Connect Install Guide. Guide can be found under the Sidewinder EXM manual section at www.elkhartbrass.com.

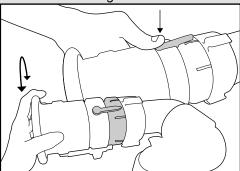
2. A. Position monitor discharge elbow parallel to ground. Ensure gasket is inside nozzle swivel.



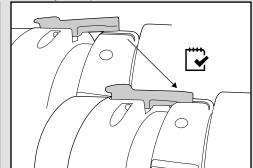
B. Hand tighten nozzle to monitor using swivel end piece.



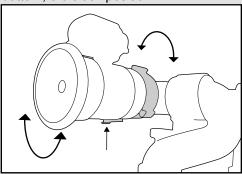
C. Adjust flow by pressing down on locking lever and rotating nozzle to desired flow setting.



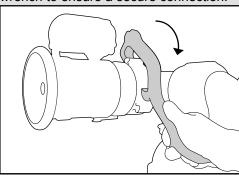
D. Confirm that locking lever is snapped securely into position.



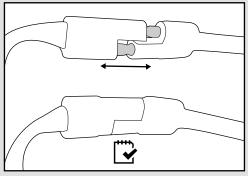
E. Loosen swivel and reposition nozzle so the locking lever is on the very bottom; 6 o'clock position.



F. Tighten swivel using a spanner wrench to ensure a secure connection.



G. Connect nozzle and monitor two-way connectors.



3. Confirm that all connections are tight and all electrical connections have been reconnected. If installing additional components, such as controllers, you may choose to double check the connections after everything has been installed.



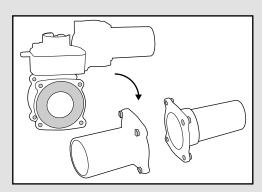
Joystick Controller

OEM Interface Module



Position Feedback Display

A. Install valve into plumbing. Torque adapter bolts to spec using Figure 1.



NOTE: If you need to change the orientation of the electric actuator on top of the valve, follow the instructions on page 16 of the Unibody Valve Manual (98311000). Manual can be found at: www.elkhartbrass.com/down loads/manuals

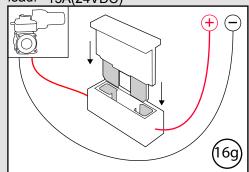
Tighten Adapter Bolts using a cross pattern



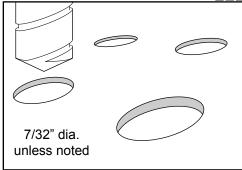
Valve	Torque
EB15	25-30 ft-lbs
EB20	25-30 ft-lbs
EB25	25-30 ft-lbs
EB30	38-40 ft-lbs
EB35	38-40 ft-lbs
EB40	60-70 ft-lbs

Figure 1: Torque Specs

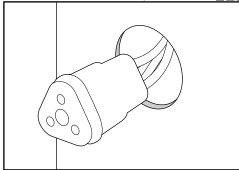
B. Add a 30A(12VDC)* fuse between RED controller lead and positive power lead. *15A(24VDC)



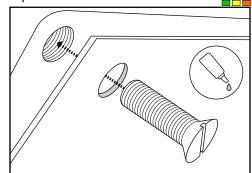
5. A. Follow mounting templates on page 30 of the instruction manual for hole diameters and dimensions.



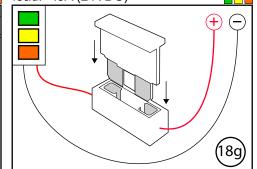
B. Drill holes for CAN network and power cables for each components' leads behind each component.



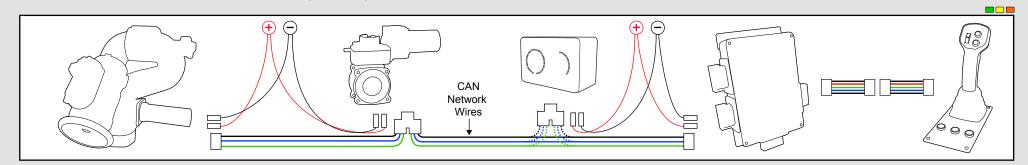
C. Mount components to panel using 10-24 x 1/2" screws. Use Loctite 242 or equivalent.



D. Add a 1A (12VDC)* fuse between red component lead and positive power lead. *.5A (24VDC)



6. A. Connect entire CAN network together using 18-22 AWG. Ensure every component connected to the CAN network is connected in between 2 end components that have CAN termination. Please refer to the BLUE, GREEN, and BLACK lines as the CAN wires below.



(O)

NOTE: You will also need to calibrate the valve before use. While you are **NOT** in setup mode, press and <Preset> hold and <Close> for approximately 5 seconds. The will valve automatically start to calibrate itself.

following The steps are optional (O).

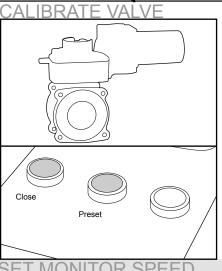
Pressina the <Osc> button will cycle through the monitor motor speed options:

LEDs - Ver / Hor

- 0 Fast / Fast 1 - Slow / Fast
- 2 Fast / Slow
- 3 Slow / Slow

Lower Left: Move to top/right corner of the lower left zone. <Preset>. hold press <Close>. and release both.

Lower Right: Move to top/left of the corner lower right zone, <Preset>, <Open>, and release both.



FP-OI

Lower Right Zone:

Lower Lef

Left Travel Limit

Lower Left Zone

Top right corner

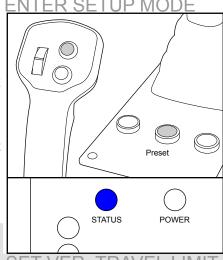
Lower Right

Zone

Right Travel Limit

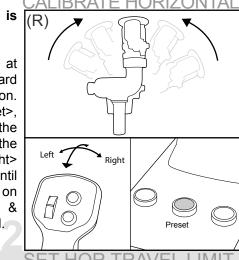
Press and hold <Aux> and <Pre><Pre>et> until the blue status LED on monitor box turns on.

NOTE: Changes made will not take effect until after exiting setup mode.



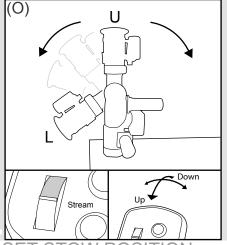
This step required (R).

Aim monitor at forward center "zero" position. <Preset>, Hold then move the joystick to the <Left> or <Right> and hold until status LED on monitor blinks & returns to solid.



Move monitor to a travel limit position. Hold <Stream>, and move the joystick forward to set the lower limit, and pull back to set the upper limit.

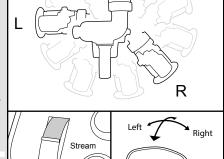
MAX travel of 135° below the pre-calibrated "zero" position.



Move monitor to travel limit position. Hold <Stream>, and move the joystick left to set the left limit, and to the right to set the right limit.

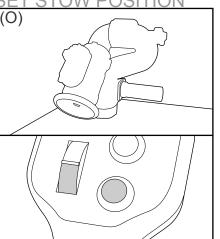
(O)

MAX travel of 175° in either direction from the calibrated "zero" position.

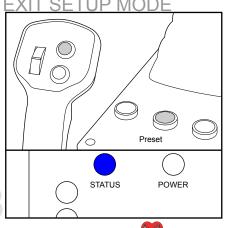


Move monitor to desired position, then press <Fog> and <Osc> at the same time to store stow а position.

Stow position must be within allowed limits of travel.



Press and hold <Aux> and <Preset> until the blue status LED on monitor box turns off.





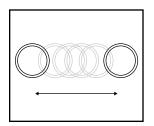
Button Press Logic: Joystick

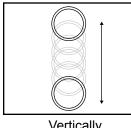
To Stow

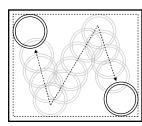
Hold <Fog> and <Osc> until monitor begins to stow.

To Oscillate

Press the <Osc> button at both extremities of the desired oscillation pattern.







Horizontally

Vertically

Two Axis Oscillation

NOTE: You can manually control nozzle position while in a single axis oscillation. Example: Up and Down will allow you to manually control the vertical axis while in a horizontal oscillation. Any direction in a two axis oscillation will stop the oscillation.

Left, Right, Up, Down

These function normally

Fog & Straight Stream

These function normally

Valve Open & Close

These function normally

Valve Preset

Opens or closes valve to a predetermined position

To Change Valve Preset

Open or close the valve to the desired position. Press and hold the <Pre><Pre>eet> button until the preset light blinks (approx 10 seconds).

Valve Auto Travel

To auto travel OPEN, hold the <Open> button, then press <Close>, and release both. The valve should fully open automatically. To CLOSE, hold the <Close> button, then press <Open>, and release both.

Joystick Layout:

